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Hybrid GWO and CS Algorithm for UPQC Positioning in the Power Distribution Network

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Abstract: Currently, Flexible Alternating Current Transmission System (FACTS) devices, particularly UPQC are established to encompass important impacts on rising power system stability. Numerous intellectual optimization algorithms were used to positioning the Unified Power Quality Conditioner (UPQC) in the power systems. Nevertheless, those optimization algorithms did not succeed to present more reliability and the feedback signal. Therefore, this work proposes a Power Quality enhancement technique that is based on a hybrid approach that connects Grey Wolf Optimization (GWO) and Cuckoo Search Algorithm (CSA). Also, the developed technique discovers the optimal position of UPQC device which focuses on the cost of UPQC, Voltage Stability Index (VSI) and power losses. The developed technique is performed in IEEE 33 and 69, test bus systems. Moreover, developed technique performance is illustrious over other exiting techniques namely GWO, Whale Optimization Algorithm (WOA), Artificial Bee Colony (ABC), Worst Solution linked WOA update (WS-WU), WS-WU, Genetic Algorithm (GA), Dragonfly (DA) and Firefly (FF). The developed technique performance is efficiently shown by its performance and convergence analysis.

Keywords: UPQC; Power Loss; Power Quality; VSI; Optimization Algorithm

Nomenclature									
Abbreviations	Descriptions								
FACTS	Flexible Alternating Current Transmission System								
SCIG	Squirrel Cage Induction Generator								
UPQC	Unified Power Quality Conditioner								
ABC	Artificial Bee Colony								
APFs	Active Power Filters								
CSA	Cuckoo Search Algorithm								
PQ	Power Quality								
PEMFC	Proton Exchange Membrane Fuel Cell								
PAC	Power Angle Control								
GWO	Grey Wolf Optimization								
SC	Super Capacitor								
VA	Volt-Ampere								
WS-WU	Worst Solution Linked Whale Optimization Algorithm Update								
VSI	Voltage stability Index								
FF	Firefly								
CS	Cuckoo search								
DS	Distribution System								
VA	Volt Amperes								
MGWO	Modified Grey Wolf Optimization								
DG	Distributed Generation								
OBL	Opposition-based learning								
PV	Photovoltaic								
SAPF	Shunt active power filter								

1. Introduction

The chief challenges of the smart grid are power quality. Power quality problems like harmonic distortions have been rising quickly due to the rise in the exploitation of power electronic converters [1]. For PQ problems, APFs being rapid, and dynamic, are favored over passive filters to recompense. Series Active Power Filter principally compensates to supply voltage associated PQ concerns namely voltage swell, sag, and harmonics. Conversely, Shunt Active Power Filter primarily compensates for load current associated PQ concerns like unbalance, deprived power factor, and harmonics. UPQC is the incorporation of the shunt and series Active Power Filter distributes a widespread DC link [19]. UPQC, incorporating advantages of both shunt and series Active Power Filter, compensates for the majority of PQ problems [20].

UPQC represents a multitasking power conditioner that can exploit compensation a lot of voltage disturbances of voltage fluctuations, power supply, and to avert harmonic load current from the incoming power system. It indicates a traditional power device modeled to ease disturbances that affect the sensitive loads' performance [1]. UPQC comprises of 2 voltage-source inverters through a widespread dc-link modeled in single-phase, 3-phase 3-wire, or 3 phase 4-wire configurations. The series Active Filter compensates for voltage supply disturbances for example flickers, imbalances, harmonics, swell, sag, and negative and zero sequence components. For load current distortions the shunt filter compensates for instances occurred by imbalances, harmonics, and reactive power and carries out the voltage regulation of dc link [18].

To act for voltage swells or sag, voltage harmonics, on the series side and reactive power compensation, load unbalance compensation, current harmonic compensation, and enhancement of power factor on parallel side UPQC is exploited. Conversely, the PQ issues via electrical networks possess the increased purpose of a lot of researchers; [7] has developed the control and the topology of a UPQC which can be exploited for the improvement of PQ. Also, an enhanced fuel cell-based controller of UPQC expands its ability in PQ for dual topology was examined in [8]. In [9] a 3-phase UPQC based combination of PEMFC to alleviate voltage sag and current harmonic was described. Numerous researchers encompass worked to intelligent methods to manage these FACTS like fuzzy logic controller Performance for managing SAPF was examined [10] that is fine renowned for enhancements of both performances of the steady-state and transient. The disturbing controller is exploited as an adaptive controller that shows to encompass maximum ability control DVR through an easy model.

The main contribution of a proposed technique is used for the optimal positioning and the sizing of UPQC in power DS exploiting hybridization of GWO and CS. In developed technique, opposition based learning of GWO is persuaded in CS, and consequently, the developed technique is called as hybrid GWO-CSA. The recommended technique discovers the optimal position of UPQC device by regarding power losses, cost of UPQC, and VSI. Also, the developed technique performance is evaluated with the conventional techniques such as FF, ABC, GWO, WS-WU, WOA, GA and DA, and the developed technique is analyzed in IEEE 33 and 69 test bus systems.

2. Literature Review

In 2020, Ashish Patel et al [1] developed an optimum sizing algorithm for UPQC-DG based on an enhanced PAC method that shares reactive power burden among shunt and series converters. With the exception of optimal-sizing, by the integration of the VA restricts in PAC approach to assure converters operation in modeled ratings in all circumstances. In 2020, Guilherme Masquetti Pelz et al [2], developed a Distributed Generators system incorporating a Photo Voltic system using a one-Phase to three-Phase UPQC-1PH-3PH. The scheme called DG-UPQC-1PH-3PH inserts to grid the energy created from a PV array, causative to supply loads. In addition the active power injection to the grid, DG-UPQC-1PH-3PH enhances PQ indicators, like grid voltage harmonics, voltage swells/ sags, and power factor. In 2019, S.Lakshmi Kanthan Bharathi and S. Selvaperumal [3] worked on the UPQC with an MGWO based on the Proportional Integral controller incorporated through renewable energy such as Wind turbine SCIG was developed to eliminate current and voltage harmonics imperfection accurately. Similarly, MGWO was as well used in UPQC. In 2018, Ashish Patel et al [4], proposed an enhanced control approach for by means of an unbalanced load. Shunt APF was overburdened while it unaccompanied equipment total load reactive power in UPQC. PAC algorithm aspires at effectual use of shunt and series APFs by distribution reactive power burden. Conventional PAC techniques can lead to the flow of reactive power among 2 Active Power Filters and thus consequence in UPQC overloading in attendance of unbalanced load. Here, a novel PAC algorithm was developed that evades the flow of reactive power and redundant VA load on UPQC. In 2018, Brahim Berbaoui [5], developed an optimal control approach for UPQC to enhance PQ and control efficiently equal power-sharing among series and shunt UPQC inverter in

electrical errors circumstance. A hybrid power generator that combines a PEMFC as a major energy source, and SC as a secondary source, was developed to provide for the FACT device. In 2016, Gowtham N and Dr.Shobha Shankar [6], worked on UPQC that was an integration of shunt and series APFs. The series APFs mitigates voltage based distortions when shunt active power filters alleviate current based distortion. UPQC alleviates current and voltage based distortion concomitantly and separately. UPQC enhances PQ through compensating both loads and current harmonics that thus create load voltage and source current sinusoidal at the necessary voltage level.

3. Optimal Positioning and sizing of UPQC

3.1 Objective Function

The most important characteristic following the developed PQ improvement is the UPQC position. The positioning of UPQC encompasses to fulfil objectives for getting better PQ. The objective model of the executed model is shown in eq. (1). In Eq. (4), P_{Loss} is stated [12] which shows the power loss. Moreover, O_k states conductance of k^{th} line related between i and j buses. Buses are shown by δ_i and δ_j voltage angle of i and j. In Eq. (2) [33], $UPQC_{Cost}$ is demonstrated. Moreover, R indicates the benefit rate of return, $UPQC_{Cost}$ states investment cost, O indicates the UPQC's performance restrictions in MVAr, $UPQC_{Cost}$ indicates the UPQC annual cost, mUPQC indicates the durability of UPQC's. In eq. (3) the

VSI idea is shown, where, the voltage magnitude for b^{th} bus and μ indicates small constant. The VSI must be in the limits of 0.9 to 1.1, and the penalty is supplementary added up, if there is any divergence within this range,

$$OB = min(UPQCcost + P_{Loss} + VoltageStabilityIndex)$$
(1)

$$UPQC_{Cost}(US(kVA)) = 0.00030^{2} - 0.269 D + 18822$$

$$(1-R)^{mUPQC} \times R$$
(2)

$$UPQC_{Cost_{year}} = UPQC_{Cost} \frac{(1-R)^{mUPQC} \times R}{(1+R)^{mUPQC} - 1}$$
(2)

$$VSI = \begin{cases} 1 & \text{if } V^{\min} \le V^b \le V^{\max} \\ \exp\left(\mu | 1 - V^b |\right) & \text{otherwise} \end{cases}$$
(3)

$$P_{Loss} = \sum_{k=1}^{N_{L}} P_{Lossk} = \sum_{k=1}^{N_{L}} O_{k} \left\{ V_{i}^{2} + V_{j}^{2} - 2V_{i}V_{j}\cos(\delta_{i} - \delta_{j}) \right\}$$
(4)

Equality and Inequality parameters need to be fulfilled with the proposed model, and it is stated in the following subdivision.

3.2 Equality Constraints

The reactive and active line power is to deal with concerning the bus voltage magnitude and phase angle. As a result, the active power balance in DS is shown in eq. (5), and reactive power balance is shown in eq. (6).

$$P_{H_{i}} - P_{E_{i}} - \sum_{k=1}^{N_{L}} o_{ik} \left\{ V_{i}^{2} + V_{j}^{2} - 2V_{i}V_{j}\cos(\delta_{i} - \delta_{j}) \right\} = 0$$
(5)

$$QU_{H_{i}} - QU_{E_{i}} - \sum_{k=1}^{N_{L}} p_{ik} \left\{ V_{i}^{2} + V_{j}^{2} - 2V_{i}V_{j}\sin(\delta_{i} - \delta_{j}) \right\} = 0$$
(6)

In eq. (5), P_{H_i} and P_{E_i} indicates active power which injects at system active power demand and ith bus respectively. QU_{H_i} states the reactive power, which was injected at ith bus and P_{Loss} states the total active power loss. Q_{Loss} states the reactive power loss and QU_{E_i} states reactive power system demand. o_{i-j} and p_{i-j} , states conductance and susceptance, correspondingly which are connected among i and j. V_j and V_i states voltage magnitude in cooperation of j and ibuses.

3.3 Inequality Constraints

These parameters express the system capacity and its functioning limits.

Line flow limit: This limit states maximum power transmission during the meticulous transmission line under the specified circumstance. The limits are dependent on stability or thermal deliberation. In Eq. (7) the power flow limit factor is shown whereas $SE_{\mu max}$ states the maximum value of power flow by

means of $k^{\,th}\,$ line.

$$SE_k \le SE_{max}$$
 (7)

Bus voltage limit: The consideration of bus voltage limit is regarding voltage unbalance limit and voltage magnitude limit node, equivalently. The 3 phase node parameter of the voltage magnitude limit is shown in Eq. (8).

$$V^{\min} < V < V^{\max}$$
(8)

4. Mathematical Model of UPQC

The diagrammatic model of UPQC that is modeled based on a 3-phase 4-wire voltage source converter is demonstrated in Fig 1.



Fig. 1. Schematic illustration of UPQC

In fact, UPQC is designed with series and shunt APF. Usually, shunt Active Power Filter is linked overloads for the reason of recompense complete current associated unease like reactive power compensation; load unbalances compensation, the recompense of current harmonic and regulation of dc-link voltage, power factor expansion.

The series APFs are linked using a line by a three-phase series transformer in series. This performs as a controlled voltage source that might recompense and a control voltage source for complete voltage associated unease like, voltage harmonics, and flicker, so on.

UPQC minimizes load disturbance area to a normal functioning zone using the safety of fault. Subsequently, it eases the voltage sag and unbalances, and minimizes loss of real power. 2 inverters that are linked using a single dc storage capacitor is used. Moreover, 1- inverter is installed for series voltage enclosure, and the following one is used for shunt current inclusion. The performance analysis of series inverter, and shunt inverter, follows: injected voltage magnitude via series inverter V_{se} chiefly is based on the maximum voltage sag that needs to be enhanced. The source voltage magnitude in normal conditions and voltage sag is represented as $V_s = kV_{SO}$ and $V_s = V_{SO}$ and here $k_{sag} = (1-k)$. On some state load voltage, $V_L = V_{SO} = V_s$. The essential series voltage insertion for mitigating k_{sag} p.u of voltage sag is shown in eq. (9). Using UPQC lossless, active power needed via load is shown as active power engaged from the source. In sense, $kV_sI_s = V_LI_L \cos \phi$ that proffers the source current as stated in eq. (10), whereas I_L and I_s states the compensated source-end current and the load current. VA series inverter rating is stated as eq. (11) from both eq. (9) and (10),

$$V_{sc} = \sqrt{V_L^2 + (kV_{SO})^2 - 2V_L(kV_{SO})\cos\delta}$$

= $V_r \sqrt{1 + k^2 - 2k\cos\delta}$ (9)

$$I_{s} = I_{L} \cos \phi / k \tag{10}$$

Journal of Computational Mechanics, Power System and Control

$$SE_{se} = V_{se}I_{s} = V_{s}I_{L}\cos\phi\sqrt{1 + k^{2} - 2k\cos\delta/k}$$
(11)

Eq. (12) and (13) states active and reactive power distributed with a series inverter, correspondingly, whereas, $\theta_{se} = 180^{\circ} - \tan^{-1}(\sin \delta/1 - \cos \delta)$ [12].

$$P_{se} = SE_{se} \cos \theta_{se} \tag{12}$$

$$QU_{se} = SE_{se} \sin \theta_{se} \tag{13}$$

As stated in Eq. (14), the phrase of recompense current via shunt inverter, $\,I_{sh}\,$ is stated.

$$I_{sh} = \sqrt{I_s^2 + I_L^2 - 2I_sI_L\cos(\phi - \delta)}$$

= $I_I \sqrt{1 + \cos^2 \phi / k^2 - 2\cos\phi\cos(\phi - \delta) / k}$ (14)

Moreover, as stated in Eq. (15) and (16), shunt inverter regulates harmonic present in load end, whereas I_{sh}^{fu} states fundamental element, I_L^{fu} states basic element, I_L^{di} states distortion element, THD_L states the load current THD, THD_{sh} states the shunt inverter current's Total Harmonic Distribution. Hence, shunt recompense current's Root Mean Square value is shown in eq. (17).

$$I_{L}^{di} = I_{sh}^{di}$$
(15)

$$THD_{L}I_{L}^{fu} = THD_{sh}I_{sh}^{fu}$$
(16)

$$I_{sh} = I_{sh}^{fu} \sqrt{1 + \text{THD}_{sh}^2}$$

$$= I_L^{fu} \sqrt{1 + \cos^2 \phi / k^2 - 2\cos\phi \cos(\phi - \delta) / k + \text{THD}_L^2}$$
(17)

For that reason, the explanation of the shunt inverter's VA rating is stated in eq. (18).

$$\Xi_{sh} = V_s I_{sh}$$

$$= V_s I_L^{fu} \sqrt{1 + \cos^2 \phi / k^2 - 2\cos\phi \cos(\phi - \delta) / k + THD_L^2}$$
(18)

The reactive and active powers, that are diffused using shunt inverter is demonstrated in Eq. (19) and (20). $\theta_{sh} = \tan^{-1} \{\cos(\phi - \delta) - \cos\phi / \sin(\phi - \delta)\} + 90^{\circ} - \delta$. The total reactive power which is transported using UPQC is stated in eq. (21) [12].

$$P_{\rm sh} = SE_{\rm sh} \cos \theta_{\rm sh} \tag{19}$$

$$QU_{sh} = SE_{sh} \sin \theta_{sh}$$
⁽²⁰⁾

$$QU_{UPQC} = QU_{se} + QU_{sh}$$
⁽²¹⁾

5. Proposed Technique for Optimal Sizing and Positioning of UPQC

5.1 Conventional GWO

GWO [13] is a meta-heuristic technique, imitates wolves' hunting behavior. In GWO, the optimal individual is named α wolf, second- and third-best individuals represented as β and δ wolves, correspondingly, and the other individuals, are named ω wolves. The wolf behavior of swarm encircling prey is shown in eq. (22).

$$Y(t+1) = Y_{p}(t) - B \cdot \left| D \cdot Y_{p}(t) - Y(t) \right|$$
(22)

In eq. (22), Y represents location vector of the wolf, Y_p indicates the position vector of prey t indicates the number of iterations,

$$\mathbf{B} = 2 \cdot \mathbf{a} \times \mathbf{r}_{\mathrm{l}} - \mathbf{a} \tag{23}$$

 $D = 2 \times r_2$ are coefficient, $r_1 \in [0,1]$ and $r_2 \in [0,1]$ are arbitrary number, and a is computed in eq. (24).

$$a(t) = 2 - \frac{2t}{\max_{itr}}$$
(24)

In eq. (24), max_{itr} indicates the utmost number of iterations.

In population, the locations of other individuals are updated using α , β and δ wolves as below.

$$Y_{1} = Y_{\alpha} - B_{1} \cdot |D_{1} \cdot Y_{\alpha} - Y|$$

$$(25)$$

$$V_{\alpha} = V_{\alpha} - V_{\alpha}$$

$$Y_2 = Y_\beta - B_2 \cdot |D_2 \cdot Y_\beta - Y|$$

$$(26)$$

$$V = V = B |D_2 \cdot V_\beta - Y|$$

$$(27)$$

$$Y_3 = Y_\delta - B_3 \cdot |D_3 \cdot Y_\delta - Y|$$

$$(27)$$

$$Y(t+1) = \frac{I_1(t) + I_2(t) + I_3(t)}{3}$$
(28)

In eq. (25), (26) and (27), B_1 , B_2 , and B_3 are same as B, D_1 , D_2 , and D_3 are same as D.

5.2 Conventional CS

CS [18] is a comprehensively employed meta-heuristics technique, emulates breeding parasitism cuckoos behavior. A solution communicates to a cuckoo egg in CS. Throughout the iterative procedure, the novel candidate solution is formed employing Lévy flight in eq. (29).

$$Y_{i} = Y_{i} - \gamma \cdot \left| Y_{i} - Y_{g} \right| \oplus levy(\lambda) = Y_{i} + \frac{0.01\mu}{\left| v \right|^{1/\lambda}} (Y_{i} - Y_{g})$$
(29)

In eq. (29), λ indicates the Lévy flight exponent, Y_i indicates the ith solution, \oplus denotes entry-wise multiplications, Y_g indicates global optimal solution, $\gamma > 0$ indicates step scaling size, u and v denotes arbitrary numbers, and they, are satisfied by means of normal distribution [14]:

$$u\hat{N}(0,\sigma_{u}^{2})v\hat{N}(0,\sigma_{v}^{2})$$

$$(30)$$

$$\sigma_{\rm u} = \left[\frac{\sin\left(\frac{\lambda\pi}{2}\right) \cdot \Gamma(1+\lambda)}{2^{(\lambda-1)/2} \lambda \cdot \Gamma\left(\frac{1+\lambda}{2}\right)} \right]$$
(31)

In eq. (31), $\Gamma(\cdot)$ denotes Gamma function.

In addition, CS exploits detection operator to put back finds out nests through probability p_a in eq. (32) [14]:

$$Y_{i} = \begin{cases} Y_{i} + rn \cdot (Y_{j} - Y_{k}), & \text{if } p > p_{a} \\ Y_{i}, & \text{else} \end{cases}$$
(32)

In eq. (32), $p \in [0,1]$ denotes a random number Y_j and Y_k indicates the candidate solutions from the population, correspondingly.

5.3 Opposition Learning Scheme

The GWO algorithm was effectively used for technical and a lot of engineering fields [17]. Nevertheless, about [15], the conventional GWO approach is superior at local exploitation, however, reduced at global exploration. Hence, one vigorous research subject is to improve the global exploration capability of Grey Wolf Optimization. OBL [21] is a competently exploration-improved method which was comprehensively exploited meta-heuristic techniques to make stronger their global exploration capacity. The Opposition based Learning method is stated as follows:

Description 1: Opposite number. Consider y as a real number, its opposite number y' is stated in eq. (33)[16]:

$$y' = 1 + u - y$$
 (33)

In eq. (33), 1 and u denotes lower and the upper boundary of y.

Description 2: Opposite solution. Eq. (34) has the ability to comprehensive D-dimensional search space. Presumptuous that $Y = (y_1, y_2, ..., y_D)$ is a solution in D-dimensional search space. The opposite solution of Y is stated in $Y = (y'_1, y'_2, ..., y'_D)$ [16]:

$$y'_{i} = l_{i} + u_{i} - y_{i}, \quad i = 1, 2, \dots, D$$
 (34)

In conclusion, the values of fitness function are f(Y) and f(Y') are calculated.

If f(Y) is better f(Y'), Y is elected; if not, Y' is elected.

In recent times, the Opposition Based Learning approach is employed to Grey Wolf Optimization technique to progress its performance [17]. Dissimilar from [17], this paper employs OBL mode to make decision layer individuals (α , β and δ wolves) utilizing probability p_b to additional enhance population diversity. Fig 2 indicates the flow chart of the proposed model.



Fig. 2. Fow chart of the developed model

6. Results and Discussions

6.1 Experimental Procedure

The developed model was implemented in MATLAB 2017. Moreover, 2 diverse bus systems were used namely IEEE 33 and the IEEE 69 bus system. Three analyses were performed based upon the position of UPQC such as one location, two locations, and three locations. The evaluation was done with existing models such as GWO, WOA, FF, ABC, WS-WU, DA, and GA for both bus systems and consequences were accomplished.

6.2 Performance Analysis

Tables 1 and 2 summarize the performance analysis of developed technique over traditional techniques for IEEE 33 and the IEEE 69 bus system in the various numeral of location (1, 2, and 3). Here, in Table 1 and 2 accurate value shows that the proposed method attains minimized fitness value while illustrious to former techniques. Meanwhile, the performance analysis regarding the fitness evaluation is stated in Tables 1 and 2 for the three locations.

Methods				Sin	gle Objec	Multi-objective						
		VSI		P _{Loss}			UPQC _{Cost}			Final Fitness		
	Locations-Locations-Locations-Locations-Locations-Locations-Locations-Locations-Locations-Locations-Locations-											
	1	2	3	1	2	3	1	2	3	1	2	3
	44.105	40.781	40.303	388.87	381.46	373.4	193.43	108.61	75.659	515.4	430.85	478.17
ABC	44.555	40.761	40.754	383.41	381.34	381.41	101.35	108.38	75.446	517.13	430.37	487.59
FF	44.856	40.739	40.483	388.87	380.99	374.74	193.43	108.55	75.568	515.15	430.37	479.68
GWO	44.048	40.074	40.147	385.86	373.37	373.37	198.18	110.03	75.686	518.07	413.46	478.1
WOA	44.788	40.481	40.108	388.88	374.8	373.37	193.43	107.73	75.686	515.08	411.9	478.06
WS-WU	44.555	40.053	40.474	383.41	373.37	375.73	101.35	110.03	74.57	517.13	413.44	479.77
GA	44.987	40.478	40.643	388.8	374.74	373.4	193.56	108.04	83.614	515.44	413.15	485.55
DA	44.788	40.486	40.034	388.88	374.93	373.37	193.41	107.44	75.686	515.08	411.74	477.98
Proposed algorithm	44.888	40.562	40.032	388.03	365.02	372.12	102.33	105.32	73.23	514.44	410.74	475.98

Table 1: Analysis of the developed and existing techniques in IEEE 33bus system

Table 2: Analysis of the developed and existing techniques in IEEE 69 bus system

	Single objective										Multi-objective		
Methods		VSI		P _{Loss}			UPQC _{Cost}			Final Fitness (OB)			
	Locations-	Locations-	Locations	Locations	Locations-	Locations-	Locations	Locations-	Locations	Locations-	Locations	Locations-	
	1	2	3	1	2	3	1	2	3	1	2	3	
ABC	33.318	31.966	31.966	316.89	303.8	303.81	305	108.83	85.853	553.31	533.39	500.53	
FF	33.308	33.308	31.968	316.53	316.51	303.6	199.18	105.83	85.866	538.99	553.55	500.33	
GWO	33.318	31.968	31.958	316.89	303.89	303.35	305	108.55	85.835	553.31	533.3	500.03	
WOA	33.318	33.318	33.013	316.89	316.89	305.55	305	106.86	85.895	553.31	556.08	503.35	
WS-WU	33.336	31.988	19.193	330.96	303.3	300.61	183.36	106.86	85.851	536.65	533.15	395.65	
GA	33.331	33.063	31.968	330.96	306.58	303.89	183.36	105.33	85.689	536.65	533.96	500.55	
DA	33.336	31.968	31.968	330.96	303.89	303.89	183.36	108.55	85.686	536.65	533.3	500.55	
Proposed	33.336	19.368	19.193	330.96	303.65	300.61	183.36	108.5	85.851	536.65	530.31	395.65	
algorithm													

7. Conclusion

The most important aspire of this article is to present an enhancement of the PQ model which was based on hybrid, GWO, and CSA for optimal sizing and the location of UPQC in power DS. The best solution was designed based upon the opposition based learning model of GWO in CS and hence, the developed technique was called Hybrid GWO -CS. In addition, the developed Hybrid GWO -CS algorithm discovers the optimal position of the UPQC device by taking into consideration of the power losses, UPQC cost, and VSI. In addition, the developed technique performance was analyzed in IEEE 33and 69, bus systems, and they were differentiated over other conventional techniques such as FF, ABC, WOA, GWO, GA WS-WU, and DA and the outcomes were obtained. Thus, the performance of the developed model was verified resourcefully by experimentation analysis. To optimize performance and power systems stability and to conquer PQ issues, optimal sizing and the position of UPQC in power system was deployed exploiting the developed method.

Compliance with Ethical Standards

Conflicts of interest: Authors declared that they have no conflict of interest.

Human participants: The conducted research follows the ethical standards and the authors ensured that they have not conducted any studies with human participants or animals.

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